Pueblo Pseudo-Boolean SAT Solver

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1. Introduction

This document is a brief description of the Pueblo Pseudo-Boolean (PB) Solver version 1.5. This solver is developed at the University of Michigan, Ann Arbor, MI by Hossein Sheini, supervised by Professor Karem A. Sakallah. For details on the algorithms adopted in Pueblo the reader is referred to [1]. The solver is available for download at

http://www.eecs.umich.edu/~hsheini/pueblo.

Pueblo is an extension to MiniSAT 1.12 [2]. The implementation details, covered in this document, should be read together with the MiniSAT description presented in [2]. Note that Pueblo can solve both PB satisfiability and optimization problems and has the capability to handle integer coefficients that can be represented with at most 32 bits.

2. Constraints

Exploiting the capability of MiniSAT to handle arbitrary constraints over Boolean variables through its *Constr* abstract base class, we added a *PseudoBool* constraint class in addition to its existing *Clause* constraint class. Unique procedures for propagating and calculating reasons for this class of constraints are presented in Figure 1. Using the base class enables Pueblo to use all of MiniSAT's solving procedures independent of the type of constraint being handled. These *PseudoBool* constraints are either created at the beginning of the search or learned through PB learning procedure. Each *PseudoBool* constraint is created or learned using the *PB_new* procedure, presented in Figure 2.

3. Accumulator

The accumulator is the PB constraint that contains the resolvent of the cutting plane based PB learning procedure. The PB learning process starts with the violated constraint considered as the accumulator and continues by adding it to the implying constraints and saving it back in itself. In order to avoid searching for variables, the accumulator is implemented as an array whose size is equal to the number of problem variables. In this scenario, CNF learning consists of detecting and separately storing the false literals of the accumulator. Details of the accumulator class are presented in Figure 3.

4. Pueblo Solver

Pueblo major modifications in MiniSAT solving procedure are listed below:

class PseudoBool : public Constr int rhs int watchsum int amax float activity **bool** learnt Vec<PBTerm> terms - PBTerm comprises of a literal, a coefficient and watched bool. - terms is sorted based on coefficients **bool** propagate(**Solver** S, **lit** p) $int p_idx = terms.index(p)$ terms[p_idx].unwatch(this) - update watchsum for(int i = 0; i < size() && watchsum < amax + rhs; i++)Lit lit = terms[i]. lit $if(S.value(lit) \neq l$ False && !terms[i].watched()) terms[i].watch(S, this) - check for conflict if (watchsum < rhs_goal) terms[p_idx].watch(S, this) return FALSE- check for satisfiability $if(watchsum \ge amax + rhs)$ return True for(int i = 0; i < size(); i++)Lit lit = terms[i]. lit*int* coeff = PBTerms[i].*coeff* $\mathbf{if}(\mathrm{watchsum} \geq \mathrm{coeff} + \mathrm{rhs}) \ \mathbf{break}$ $if(S.value(lit) == l_Undef)$ if(!S.enqueue(lit, this)) terms[p_idx].watch(S, this) return False - conflict in the Solver return True *void* calcReason(Solver S, lit p, vec<lit>out_reason) - all learned constraints are initially active if (learnt) S.pbBumpActivity(this) - calculate the multiplier to eliminate p from accumulator *int* mul = (p == lit_Undef) ? 1 : S.accumulator.coeff(var(p)) S.accumulator.goal += mul * rhsfor (int i = 0; i < size(); i++) lit = terms[i].litif(lit == p)S.accumulator.goal - = mul*terms[i].coeffcontinue - adds this literal to the accumulator UpdateAccumulator(S, mul, terms[i].lit, terms[i].coeff) - saves the false literals for CNF learning if (S.value(lit) == l_False) out_reason.push(\neg lit)

Figure 1. Implementation of *PseudoBool* constraint class in Pueblo

4.1 Learning

Pueblo adopts the same learning flow as in MiniSAT augmenting it with cutting plane generation (PB learning) at each step. At each step in the backward traversal of the implication graph, the CNF or PB constraint involved in that implication is added to the

Figure 2. Implementation for creating and adding new *PseudoBool* constraints in Pueblo

```
bool PB_new(Solver S, int goal, Vec<lit_coef> pbs, PseudoBool out, Clause c, bool learnt)
out = new PseudoBool
out.rhs = goal
for (int i = 0; i < pbs.size(); i++)
   out.terms[i].lit = Lit(pbs[i].lit)
   if(pbs[i].coef < 0)
       out. rhs += abs(pbs[i].coef)
       out.terms[i].lit = \neg out.terms[i].lit
   out.terms[i].coeff = abs(pbs[i].coef)
sort(out.terms, size())
if (out.terms[0].coeff == out.rhs \&\& out.terms[size()].coeff == out.rhs) ||
  out.rhs == 1) - checking if PB constraint is equal to a CNF clause
   bool ret = convertPBtoCNF(S, out, c, learnt) - creates clause with literals in terms of out
   xfree(out)
   return ret
out.amax = out.terms[0].coeff
out.learnt = learnt
if(out. rhs == 0) return TRUE
for (int i = 0; i < size(); i++) - setting up the watch list
   Lit lit = out.terms[i].lit
   if (out.watchsum < out.rhs + out.amax) out.terms[i].watch(S, this)
   if (out.watchsum \geq out.rhs + out.amax) break
if (out. watchsum < out. rhs) return FALSE
if(out.watchsum < out.rhs + out.amax)
   for(int i = 0; i < size(); i++)
       Lit lit = out.terms[i].lit
       if(S.value(lit) == l_Undef)
          if(out.watchsum \ge out.terms[i].coeff + out.rhs) break
          if (!S. enqueue (lit)) return FALSE
if(learnt) S.varBumpActivity(lit, coeff/out.rhs)
return True
```

accumulator while performing MiniSAT's *calcReason()* routine to eliminate the implied literal. The cutting plane is saved in the accumulator while the learned CNF clause is stored in the *out_reason* following the learning procedure of MiniSAT (refer to Figure 1). If an over-satisfaction is detected in the accumulator, the step resulting in over-satisfaction is undone and replaced by adding the weakened CNF clause to the accumulator. The learning stops when the first UIP is reached as detected by MiniSAT *analyze* procedure. The details of conflict analysis procedure of Pueblo based on the *analyze* method of MiniSAT is presented in Figure 4.

4.2 Backtracking and Constraint Recording

In Pueblo, the lowest decision level at which the learned PB constraint is unit is determined by checking the PB unit invariant [1] at each decision level. If such decision level was found, the solver backtracks to the minimum level between this level and the *backtrack_level* computed in MiniSAT's *analyze* routine. Otherwise, the highest decision level at which the learned PB constraint is not violated is determined and the solver backtracks to that level or the *backtrack_level*, whichever lower. This procedure is demonstrated in Figure 5. Both

Figure 3. Implementation of the *accumulator* class in Pueblo



learned PB and CNF constraints are recorded and their watched literals are properly setup, as demonstrated in Figure 6.

4.3 Activity Heuristics

The variable activity heuristic of MiniSAT is extended to PB constraints in such a way that it recognizes the coefficient of each variable in the learned constraint. Therefore, the activity of each variable that is present in a newly learned PB constraint is increased by the ratio of its coefficient to the right-hand side of that PB constraint.

4.4 Constraint Removal

In Pueblo, the number of active PB constraints is periodically reduced to a fixed number of constraints. This procedure basically removes all PB constraints that are not *locked* (to an implication) and are less active than a pre-set threshold limit. This limit is increased at each restart. Through our experiments on benchmarks used in the PB'05 evaluation [3], we found that an initial threshold of 50 and a growth rate of 10% produces the best results.

References

- H. M. Sheini and K. A. Sakallah, "Pueblo: A hybrid pseudo-boolean sat solver," Journal on Satisfiability, Boolean Modeling and Computation (JSAT), vol. 2, p. 61, 2006.
- [2] N. Eén and N. Sörensson, "An extensible SAT-solver." in SAT, 2003, pp. 502–518.

Figure 4. Implementation for conflict analysis method in Pueblo

```
void analyze(Constr confl, Vec<Lit> out_learnt, int out_btlevel)
Vec < char > seen = analyze_seen, seen.growTo(nVars(), 0)
int pathC = 0
Lit p = lit_Undef
Vec<Lit>p_reason
bool in PB = FALSE
out_learnt.push()
out\_btlevel = 0
do
    if(inPB)
        - finding the multipliers to generate the cutting plane such that p is removed
        int mul = confl.terms.getCoeff[var(p)]
        accumulator.multiplyBy(mul)
    p_reason.clear()
    confl.calcReason(this, p, p_reason)
    - check if accumulator is satisfied and if so undo adding and replace with weakened confl
    accumulator.checkOverSatisfaction(confl)
    for (int j = 0; j < p_reason.size(); j++)
        Lit q = p\_reason[j]
        if (!seen[var(q)])
           \operatorname{seen}[\operatorname{var}(q)] = 1
           if (level[var(q)] == decisionLevel())
               pathC++
           else if (level[var(q)] > 0)
               out_learnt.push(\neg q)
               out_btlevel = :: max(out_btlevel, level[var(q)])
    - Select next constraint to look at:
    do
        p = trail.last()
        confl = reason[var(p)]
        - check if this literal should be removed from the accumulator
        inPB = accumulator.coeff(var(p)) \neq 0 \&\& (value(accumulator.lit(var(p)))) == l_False
        undoOne()
    while(!seen[var(p)])
    \operatorname{seen}[\operatorname{var}(\mathbf{p})] = 0
    pathC-
while (pathC > 0)
out\_learnt[0] = \neg p
```

[3] Pseudo-Boolean Evaluation PB'05, http://www.cril.univ-artois.fr/PB05/.

Figure 5. Implementation of PB backtracking in Pueblo

void undoPB()
accumulator.normalize() - convert all coefficients to positive
$int $ tmp_lhs = accumulator.goal
$for(int i = root_level; i < decisionLevel(); i++)$
- subtracts the sum of coefficients in the accumulator became false at level i
$tmp_lhs - = accumulator.sumAssignedFalseAtLevel(i)$
- check if accumulator is unit/conflict at this level
$if(tmp_lhs < accumulator.goal + accumulator.amaxAtLevel(i))$
$if(tmp_lhs < accumulator.goal) - no unit level exists$
$bt_level = i-1$
$else bt_level = i$
break
$cancelUntil(::max(bt_level, root_level))$

Figure 6. Implementation of conflict-induced constraint recording method in Pueblo

$bool \text{ recordPB}(Vec < Lit > \text{clause}, int \text{ backtrack_level})$
<i>PseudoBool</i> pb
Clause c
Vec < Lit > PBLits - literals in the learned PB constraint
accumulator.getLiterals(PBLits)
undoPB()
if (! <i>PBnew</i> (this, PBLits, pb, c)) return TRUE - learn the PB constraint
$\mathbf{if}(\mathrm{pb} \neq \mathrm{NULL})$
$pb_learnts.push(pb)$
pbDecayActivity()
$\mathbf{if}(\mathbf{c} \neq \mathrm{NULL})$
learnts.push(c)
claDecayActivity()
Clause CNFlearnt
bool CNFunit = False
$if(decisionLevel() > backtrack_level)$
cancelUntil(::max(bt, root_level)) - backtrack to earlier level
CNFunit = TRUE
$check(Clause_add(this, clause, CNFlearnt))$ - $learn the CNF clause$
if (CNFunit) <i>check</i> (<i>enqueue</i> (clause[0], CNFlearnt))
$if(CNFlearnt \neq NULL)$
learnts.push(CNFlearnt)
claDecayActivity()
return False